

In the Specification:

Please amend the paragraph of the specification beginning at page 8, line 18, as follows:

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B1 The beam body 260 includes a bend 268 that divides the beam body 260 into a first region 270 and a second region 272. The first region 270 is somewhat flat beam shaped and includes a proximal area that is secured to the actuator arm 36 (illustrated in Figure 1) and a distal area that cantilevers away from the actuator arm 36. The second region 272 is also somewhat flat beam shaped. In a relaxed condition, the second region 272 is at an angle relative to the first region 270. The amount of the angle can be varied to suit the design requirements of the load beam 256. For example, suitable angles can be between six and twelve degrees. The beam body 260 can include one or more apertures that reduce the mass of the beam body 260, and many other features. For example, the beam body 260 can include the lifting feature 242 for load/unload operations, one or more limiters for better shock performance, and load beam ~~stiffners~~ stiffeners such as rails.

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Please amend the paragraph of the specification beginning at page 11, line 8, as follows:

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B2 Stated another way, the present invention utilizes a composite, laminated adjuster 240 with layers 262, 264 having different coefficients of thermal expansion and modulus of elasticity to automatically vary and control gram load as temperature changes and control the flying height over a relatively large range of temperatures. As a result thereof, the present invention thermally controls gram load to maintain the slider with a desired flying height range. The desired flying height range can vary. For example, the desired flying height range can be between approximately 0.3 micro-inches and 0.6 micro-inches. Therefore, the drive can be exposed to more critical environmental temperatures during operation and the performance and reliability is enhanced.

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